

<u>Overview</u>

- Antialiasing Techniques
 - Super sampling
 - Area sampling
 - unweighted
 - weighted
- Clipping
 - Cohen-Sutherland line clipping algorithm
 - Liang-Barsky line clipping algorithm
 - Sutherland-Hogeman polygon clipping



<u>Antialiasing</u>

Aliasing, jagged edges or staircasing can be reduced by:

- Higher screen resolution
 - Need a huge frame buffer
- Antialiasing techniques

 Vary pixel intensities along to smooth the edge.





- Super Sampling
 - Compute intensities at sub-pixel grid positions and combine the results to obtain the pixel intensity.
- Unweighted Area Sampling
 - Find pixel intensity by calculating the areas of overlap of each pixel within the objects to be displayed.
 - Pixel intensity is proportional to the amount of area covered.



- Weighted Area Sampling
 - Define a weighting function that determines the influence on the intensity of the pixel.
- Pixel Phasing
 - Lines are smoothed by moving the electron beam to a closer approximate of the mathematical line.



<u>Supersampling</u> (zero line width)

- Example: a straight line on a gray scale display
- Divide each pixel into sub-pixels.
- The number of intensities are the max number of sub-pixels selected on the subpixel line segment within a pixel.



Subpixels selected by Bresenham's algorithm



<u>Supersamling</u> (finite line width)

- The intensity level for each pixel is proportional to the number of sub-pixels inside the polygon representing the line area.
- Line intensity is distributed over more pixels.





<u>Supersamling</u> (finite line width)

Disadvantages

- More calculations involved to identify interior pixels.
- Positioning of the line depends on the slope of the line.
 - 45° line centered in polygon
 - Horizontal or vertical line
 - line path on polygon boundary
 - |m| < 1
 - line path closer to lower boundary
 - -|m| > 1
 - line path closer to upper boundary





- 1. The intensity of a pixel decreases as the distance between the pixel center and the edge increases.
- 2. The primitive must intersect the pixel to have some effect.
- 3. Equal areas contribute equally to the pixel intensity.





- Equal areas can contribute to unequal intensity. (We change property 3).
- Circular pixel geometry.

Weighting (Filter) Function

- Determines the influence on the intensity of a pixel of a given small area dA of a primitive.
- This function is constant for unweighted and decreases with increasing distance for weighted.
- Total intensity is the integral of the weighting (filter) function over the area of overlap.
- W_s is the volume (always between 0 and 1)
- $I = I_{max} \bullet W_s$



Unweighted Area Sampling

Box Filter:

- W_s is a wedge of the box.
- Height of the box normalizes to 1 (box volume = 1)
- A thick line covering the entire pixel has intensity:
- $I = I_{max} \bullet 1 = I_{max}$





Cone Filter:

- A circular cone, where the base is the radius of the unit distance of the integer grid.
- Rotational symmetry.
- Linear decrease of the function with radial distance.
- Normalized to 1 (volume under entire cone is 1)





Filter Functions

- Optimal filters are computationally more expensive.
- Cone filters are a very reasonable compromise between cost







Anti-Aliasing

Pixel Phasing:

• Pixel positions can be shifted by a fraction of a pixel diameter (1/4, 1/2, or 3/4) to plot points closer to the mathematical line.

Line Intensity Differences:

- The diagonal line appears less bright than the horizontal. (The diagonal line is longer than the horizontal line by a factor of sqrt(2)).
 - Total intensity is proportional to their length.



Clipping Algorithms

Line Clipping:

- Cohen-Suterland (encoding)
 - Oldest and most commonly used
- Nicholl-Lee-Nicholl (encoding) (more efficient)
- Cyrus-Beck and Liang-Barsky (parametric)
 - More efficient than Cohen-Sutherland

Polygon Clipping:

- Sutherland-Hodgeman (divide and conquer strategy)
- Weiler-Atherton (modified for concave polygons)

Cohen-Sutherland Line-Clipping			
1. Encode end points	1001	1000	1010
Bit 0 = point is left of window Bit 1 = point is right of window Bit 2 = point is below window Bit 3 = point is above window	0001	0000	0010
A = point is above window A	0101	0100	0110
2. If C_1 , $C_2 \neq 0$ then P_1P_2 is			
v trivially rejecte	d		
3. If $C_1 C_2 = 0$ then P_1P_2 is	C ₁ = Bit code of P1		
trivially accept	ed C ₂	= Bit cod	e of P2
4. Otherwise subdivide and go to step 1 with new segment.			





<u>Liang-Barsky</u> Line-Clipping

- More efficient than Cohen-Sutherland
- Clipping conditions:
 - A line is inside the clipping region for values of t such that:

$$x_{\min} \le x_1 + t\Delta x \le x_{\max}$$
 $\Delta x = x_2 - x_1$

$$y_{\min} \le y_1 + t\Delta y \le y_{\max}$$
 $\Delta y = y_2 - y_1$



<u>Cohen-Sutherland</u> <u>Line-Clipping</u>

- Will do unnecessary clipping.
- Not the most efficient.
- Clipping and testing are done in fixed order.
- Efficient when most of the lines to be clipped are either rejected or accepted (not so many subdivisions).
- Easy to program.
- Parametric clipping are the most efficient. (Liang-Barsky and Cyrus-Beck)



Liang-Barsky Line-Clipping

• The infinitely line intersects the clip region edges when:

$$t_{k} = \frac{q_{k}}{p_{k}} \text{ where } \begin{array}{l} p_{1} = -\Delta x \quad q_{1} = x_{1} - x_{\min} \quad \text{Left boundary} \\ p_{2} = \Delta x \quad q_{2} = x_{\max} - x_{1} \quad \text{Right boundary} \\ p_{3} = -\Delta y \quad q_{3} = y_{1} - y_{\min} \quad \text{Bottom boundary} \\ p_{4} = \Delta y \quad q_{4} = y_{\max} - y_{1} \quad \text{Top boundary} \end{array}$$



Liang-Barsky Line-Clipping

- When $p_k < 0$, as *t* increases line goes from outside to inside entering
- When $p_k > 0$, line goes from inside to outside exiting
- When $p_k = 0$, line is parallel to an edge
- If there is a segment of the line inside the clip region, a sequence of infinite line intersections must go: entering, entering, exiting, exiting



<u>Liang-Barsky</u> Line-Clipping

- Set $t_{min} = 0$ and $t_{max} = 1$.
- Calculate the *t* values:
 - If $t < t_{min}$ or $t > t_{max}$ ignore it.
 - Otherwise classify the *t* values as entering or exiting.
- If $t_{min} < t_{max}$ then draw a line from:

 $(x_1 + \Delta x \cdot t_{min}, y_1 + \Delta y \cdot t_{min})$ to $(x_1 + \Delta x \cdot t_{max}, y_1 + \Delta y \cdot t_{max})$







<u>Liang-Barsky</u> Line-Clipping

- We have $t_{min} = 1/4$ and $t_{max} = 3/4$
- If t_{min} < t_{max}, there is a line segment
 compute endpoints by substituting t values
- Draw a line from (-5+(20)·(1/4), 3+(6)·(1/4)) to (-5+(20)·(3/4), 3+(6)·(3/4))





Liang-Barsky Line-Clipping

- We have $t_{min} = 4/5$ and $t_{max} = 2/3$
- Q-P = (2+8,14-2) = (10,12)
- $t_{min} > t_{max}$, there is no line segment do draw







<u>Suterland-Hodgeman</u> <u>Polygon Clipping</u>

Four test cases:

- 1. First vertex inside and the second outside (in-out pair)
- 2. Both vertices inside clip window
- 3. First vertex outside and the second inside (out-in pair)
- 4. Both vertices outside the clip window

Concave polygons may be displayed with extra lines.





<u>Nicholl-Lee-Nicholl</u> Line Clipping

- To find which region P₂ is in, compare the slope of the line to the slopes of the clip rectangle.
- If P₁ is left of clip rectangle, then P₂ is in region Left Top if: slopeP₁P_{TR} < slopeP₁P₂ < slope P₁P_{TL}
- Number of cases explodes in 3D, making it unsuitable.



<u>Weiler-Atherton</u> <u>Polygon Clipping</u>

- Clips concave polygons correctly.
- Instead of always going around the polygon edges, we also, want to follow window boundaries.
- 1. For an outside-to-inside pair of vertices, follow the polygon boundary.
- 2. For an inside-to-outside pair of vertices, follow the window boundary in a clockwise direction.