

Review: conservation laws and Finite Volume Methods

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14 november 2011

Conservation laws

Def.: A (scalar) **conservation law** is a partial differential equation of the type

$$\frac{\partial \lambda}{\partial t} + \nabla \cdot \mathbf{f}(\lambda) = 0$$

λ : conserved quantity. Examples: density of mass, momentum (sv. *rörelsemängd*), or energy, concentration of a chemical compound.

\mathbf{f} : flux function; simplest example: $\mathbf{f} = \mathbf{u}\lambda$. The flux function is a *nonlinear* function of the conserved quantity in many interesting cases.

In integral form: for any control volume V holds

$$\frac{d}{dt} \int_V \lambda dV + \int_{\partial V} \mathbf{n} \cdot \mathbf{f}(\lambda) dS = 0$$

Conservation laws in one space dimension

Differential form:

$$u_t + f(u)_x = 0; \quad (1)$$

Integral form:

$$\frac{d}{dt} \int_a^b u dx + f(u(b, t)) - f(u(a, t)) = 0, \quad (2)$$

for any interval (a, b) .

Equation (1) is written in **conservative form**.

If everything is smooth, the chain rule yields that equation (1) also can be written in the **primitive form**

$$u_t + f'(u)u_x = 0;$$

The transport equation

Simplest example of 1D conservation law, the **transport equation**

$$u_t + cu_x = 0$$

Expresses **transport** of a function in the positive x -axis direction and has the general solution

$$u(x, t) = f(x - ct)$$

for a given (differentiable) function f .

Characteristics for the transport equation

The **characteristics** of the transport equation $u_t + cu_x$ are the lines in the (x, t) plane satisfying the equation $x - ct = x_0$,

The characteristic curves (lines) in parametric form: $(x_0 + ct, t) = (X(t), t)$, where $X(t)$ is the solution to

$$\begin{aligned}\dot{X}(t) &= c \quad t > 0, \\ X(0) &= x_0.\end{aligned}$$

The solution to the transport equation is constant along the characteristics

$$\begin{aligned}\frac{d}{dt}u(X(t), t) &= u_t(X(t), t) + u_x(X(t), t)\dot{X}(t) \\ &= u_t(X(t), t) + cu_x(X(t), t) = 0\end{aligned}$$

Characteristics for nonlinear conservation laws

Smooth solutions to nonlinear conservation laws are also constant along each characteristic curve. To see this, assume that u is a smooth solution to

$$u_t + f(u)_x = u_t + f'(u)u_x = 0.$$

Define the characteristic curves $(X(t), t)$ where $X(t)$ solves the nonlinear ODE

$$\begin{aligned}\dot{X}(t) &= f'(u(X(t), t)) \quad t > 0, \\ X(0) &= x_0.\end{aligned}\tag{3}$$

Then $u(X(t), t)$ is constant:

$$\begin{aligned}\frac{d}{dt}u(X(t), t) &= u_t(X(t), t) + u_x(X(t), t)\dot{X}(t) \\ &= u_t(X(t), t) + f'(u(X(t), t))u_x(X(t), t) = 0\end{aligned}$$

The right-hand side of (3) is constant (since $u(X(t), t)$ is constant)

Thus the characteristics are also here **straight lines**

Nonlinear conservation laws

- ▶ Discontinuities can both appear and disappear in the solution to nonlinear conservation laws
- ▶ **Shock** (sv. *stöt*): discontinuities in the solution appearing when characteristics intersect
- ▶ **Rarefaction wave** (sv. *expansionsvåg*): a discontinuity is smeared out by diverging characteristics
- ▶ Thus, an important feature of numerical schemes for conservation laws: the ability to handle discontinuities in the solution!

Finite volume methods for 1D conservation laws

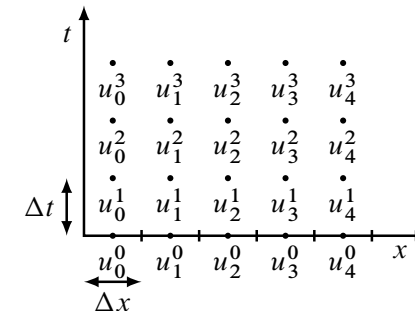
The finite volume method seeks approximations to **cell averages** at times t_n :

$$u_i^n \approx \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} u(x, t_n) dx$$

A family of **conservative, explicit** schemes:

$$u_i^{n+1} = u_i^n - \frac{\Delta t}{\Delta x} (F_{i+1/2}^n - F_{i-1/2}^n)\tag{4}$$

$F_{i+1/2}^n \approx f(u(x_{i+1/2}, t_n))$: **numerical flux function**. Defines the particular method.



The upwind method

Recall: $u_t + f(u)_x = u_t + f'(u)u_x = 0$. Thus:

$f'(u) > 0$: transport to the **right**

$f'(u) < 0$: transport to the **left**

Motivates the choice

$$F_{i+1/2} = \begin{cases} f(u_i^n) & \text{if } f'(u) > 0, \\ f(u_{i+1}^n) & \text{if } f'(u) < 0 \end{cases}$$

The flux function is evaluated in the “upwind direction.”

Yields the scheme:

$$u_i^{n+1} = \begin{cases} u_i^n - \frac{\Delta t}{\Delta x} (f(u_i^n) - f(u_{i-1}^n)) & \text{if } f' > 0, \\ u_i^n - \frac{\Delta t}{\Delta x} (f(u_{i+1}^n) - f(u_i^n)) & \text{if } f' < 0 \end{cases}$$

The Lax–Friedrich scheme

$$u_i^{n+1} = \frac{1}{2} (u_{i+1}^n + u_{i-1}^n) + \frac{\Delta t}{2\Delta x} [f(u_{i+1}^n) - f(u_{i-1}^n)]$$

Belongs to the family (4) of schemes with the numerical flux

$$F_{i+1/2}^n = \frac{1}{2} [f(u_{i+1}^n) + f(u_i^n)] - \frac{\Delta x}{2\Delta t} [u_{i+1}^n - u_i^n]$$

The upwind and Lax–Friedrich schemes behave similarly:

- ▶ Very robust and stable
- ▶ Only first-order accurate in space and time for smooth solutions: need very small Δt , Δx for accurate solutions
- ▶ Tend to smear out sharp spatial gradients

Second-order-accurate methods

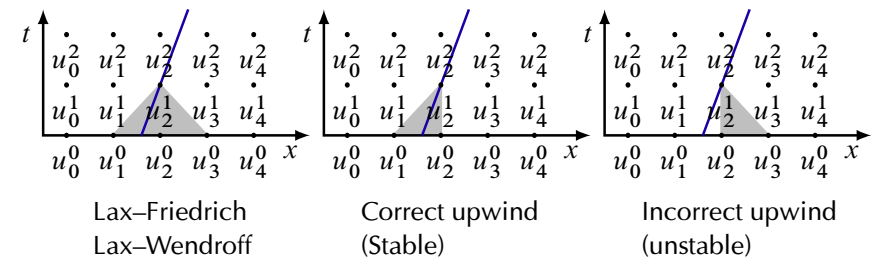
In lab 1 we tested a method that was second order in space and time: the Richtmyer two-step Lax–Wendroff method

- ▶ Performs **much** better for smooth solutions
- ▶ However, tends to generate oscillations around discontinuities

More advanced methods: “high-resolution methods”

- ▶ Second-order accurate (or better) in smooth regions of the solution
- ▶ A *limiter* or *artificial dissipation* used in the cells around discontinuities to avoid oscillations. The scheme typically reduces to an upwind-like scheme around the shock
- ▶ The scheme becomes nonlinear! Needs “sensors” that detects regions of sharp gradients.

The CFL condition



A necessary condition for stability:

The characteristics through the “update” point must pass through the **numerical domain of dependency** (the gray region)

From picture, for schemes involving points u_{i-1}^n , u_i^n , and u_{i+1}^n ,

$$\frac{\Delta t}{\Delta x} \leq \frac{1}{c}$$

Thus, it is necessary that $\Delta t \leq \Delta x/c$