Theme: Roundoff and population modeling Part II

Rules:

- During the lab, verify with the teacher that the preparatory exercises in Part I are completed.
- Each student should hand in individually completed solution.
- Use the provided answer sheet and add printouts of pictures and source code as requested.
- You may discuss the problem among fellow students. If you receive considerable help from someone, say so in your solutions.
- Do not copy solutions or code from others. Do not lend your solution or your code to other students.
- A correct solution submitted at the latest **November 11** is worth 2 bonus point on the final exam. An almost correct solution submitted in time will also entitle to bonus points, provided the solution is corrected before the final exam.

Computer exercises

- (a) In MATLAB, the command eps returns machine epsilon ε_M. More precisely, eps (x) returns the distance from abs (x) to the next larger in magnitude floating point number (of the same precision as x), and eps is a shorthand notation for eps (1). Try the command. Of what order of magnitude is ε_M?
 - (b) Is it possible to represent numbers smaller than ϵ_M ? If so, which is the smallest (positive greater than zero) number that can be represented using IEEE 754 double precision?
 - (c) What does NaN and Inf mean? Try some operations with NaN, Inf, and ordinary numbers such as Inf-Inf, Inf+Inf, 1/Inf, -1/0, NaN<-Inf, NaN>-Inf, and 2*Inf==Inf.
- 2. Predict the final value of x in each of the following statements. Motivate!

(a)	x=1;	(b) x=1;	(c) x=1;
	while 1+x>1	while x+x>x	while x+x>x
	x = x/2;	x = x/2;	x = 2 * x;
	disp(x);	disp(x);	disp(x);
	end	end	end

Test if your predictions are correct.

3. Use MATLAB to generate the sequence x_1, x_2, \ldots, x_{60} , defined by

$$x_n = \frac{7}{3}x_{n-1} - \frac{2}{3}x_{n-2}$$

with initial conditions $x_1 = 3$ and $x_2 = 1$. Plot the values using semilogy. The exact solution to the recursion with the above starting values is $x_n = 3^{2-n}$ and the general solution to the recursion is $x_n = c_1 2^n + c_2 3^{-n}$. Comment your results!

4. Sometimes, computations can be rearranged so that they are less prone to rounding errors. One way of approximating π (Archimedes) is by calculating perimeter of polygons circumscribing a circle with diameter 1. Starting with hexagons and doubling the sides at each step the length of each side of the polygon follow the recursion $t_0 = 1/\sqrt{3}$

$$t_{n+1} = \frac{t_n}{\sqrt{t_n^2 + 1} + 1}$$
, or alternatively $t_{n+1} = \frac{\sqrt{t_n^2 + 1} - 1}{t_n}$

The approximation of π in step *n* is given by $2^n \cdot 6t_n$. Try both versions and explain why one of the above recursions is less error prone.

5. The derivative f' of a smooth function f at a point x is defined as the limit

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

This limit can be approximated by the finite difference approximation

$$D_{\Delta x}^{+}f(x) = \frac{f(x + \Delta x) - f(x)}{\Delta x},$$
(1)

where $\Delta x > 0$ is a real number. In exact arithmetic it holds that $D_{\Delta x}^+ f(x) \to f'(x)$ as $\Delta x \to 0$. However, we are working with floating point arithmetic so due to cancelations one has to be careful when choosing the step Δx . Let $f(x) = e^x$ and approximate f' using the finite difference approximation (1) at x = 1 using $\Delta x = 10^{-n}$ for n = 1, 2, ... and plot the error $|D_{\Delta x}^+ f(x) - f'(x)|$ as a function of Δx .

If you have time, try using other functions. Can you find a rule of thumb on how to choose Δx to obtain a good approximation of the derivative?

- 6. Write a MATLAB function logmap (x0, r, k) that returns the vector $\mathbf{x} = [x_0, x_1, x_2, ..., x_k]^T$ for the logistic map, where x0 is the initial condition, r is the constant r, and k is the number of iterations. Plot the results as time series of x_n against n for some sensible initial value $x_0 (= 0.1)$, k = 100 iterations, and $r \in \{2.8, 3.3, 3.5, 3.9\}$. Characterize the orbits \mathbf{x} as regular or irregular.
- 7. Write a MATLAB function that returns $\boldsymbol{\delta} = [\delta_1, \delta_2, ..., \delta_k]^T$ where $\delta_i = |x_i y_i|$ with x_i the values returned by iterating the logistic map and y_i the values returned by iterating $y_{n+1} = r y_n r y_n^2$. Plot $\boldsymbol{\delta}$ for some sensible initial values $x_0 = y_0 (= 0.1)$, k = 200 iterations, and $r \in \{3.3, 3.9\}$. Give an interpretation of the results.
- 8. In spite of the above, roundoff errors rarely cause problems in practical calculations. There are, however, two instances as where roundoff effects may cause problems:
 - Problems that are inherently sensitive to disturbances in data regardless of which numerical algorithm that is used (ill-conditioned problems).
 - Algorithms sensitive to round-off even when applied to a well-conditioned problem (numerically unstable algorithms). Such algorithms should be avoided if possible!

Classify problems 4, 5, and 7 above as ill-conditioned or numerically unstable.